

Amendments to the Claims:

This listing of claims will replace all prior versions, and listings, of claims in the application:

Listing of Claims

1. (presently amended) A computerized method for manipulating a plurality of control points, the plurality of control points defining a surface and forming a plurality of rows along two non-parallel directions U and V, the method comprising:
adjusting the position of a control point in an intermediary row in the U direction to provide a smooth transition from the row of control points corresponding to a first edge along the U direction to a row of control points corresponding to a second edge along the U direction while retaining positions of control points in said first and second edges;
adjusting the position of the control point in an intermediary row in the V direction to provide a smooth transition from the row of control points corresponding to a first edge along the V direction to a row of control points corresponding to a second edge along the V direction while retaining positions of control points in said first and second edges; and
computing the new position of the control point based on the corresponding adjusted positions of the control point in the intermediary row in the U direction and the control points in the intermediary row in the V direction;
wherein the surface is selected from the group consisting of a Béziars surface and a Nurbs surface, and wherein the surface is represented in a CAD system.
2. (cancelled.)
3. (cancelled.)

4. (presently amended) The computerized method of claim 2 wherein the surface comprises a three-dimensional surface.
5. (presently amended) The computerized method of claim 1 wherein computing the new position additionally comprises averaging the adjusted position of the control point in the intermediary row in the U direction and the adjusted position of the control point in the intermediary row in the V direction.
6. (presently amended) The computerized method of claim 1 further comprising:
determining a reference axis for the first edge along the U direction, the second edge along the U direction, the first edge along the V direction, and the second edge along the V direction, wherein the method of determining the reference axis comprises:
for each edge:
determining an X vector comprising a first vector point located at a first extremity of the edge and a second vector point located at a second extremity of the edge;
determining a Z vector comprising the average of two extreme vectors orthogonally adjusted to the X vector, wherein the two extreme vectors comprise a vector formed by an extremity point and its neighbor; and
determining a Y vector comprising the vectorial product of the X vector and the Z vector.
7. (presently amended) The computerized method of claim 6 wherein adjusting the position of a control point in an intermediary row in the U direction comprises adjusting the control point using the reference axis for the first edge along the U direction and the second edge along the U direction; and wherein adjusting the position of a control point in an intermediary row in the V direction further adjusting the control point using the reference axis for the first edge along the V direction and the second edge along the V direction.

8. (presently amended) The computerized method of claim 1 further comprising:

determining if a row of control points corresponding to a first edge along the U direction belongs in a first U plane;
determining if a row of control points corresponding to a second edge along the U direction belongs in a second U plane; and
adjusting the control point using the first U plane and the second U plane, wherein the adjustment only occurs if the row of control points corresponding to the first edge along the U direction belongs in the first U plane and the row of control points corresponding to the second edge along the U direction belongs in the second U plane.

9. (presently amended) The computerized method of claim 8 further comprising:

computing an adjusted U plane for the control point to provide a smooth transition between the first U plane and the second U plane; and
wherein adjusting the control point using the first U plane and the second U plane comprises projecting the control point on the adjusted U plane.

10. (presently amended) The computerized method of claim 8 further comprising:

determining if a row of control points corresponding to a first edge along the V direction belongs in a first V plane;
determining if a row of control points corresponding to a second edge along the V direction belongs in a second V plane; and
adjusting the control point using the first V plane and the second V plane, wherein the adjustment only occurs if the row of control points corresponding to the first edge along the V direction belongs in the first V plane and the row of control points corresponding to the second edge along the V direction belongs in the second V plane.

11. (presently amended) The computerized method of claim 10 further comprising:
computing an adjusted V plane for the control point to provide a smooth transition between
the first V plane and the second V plane;
wherein adjusting the control point using the first V plane and the second V plane comprises
projecting the control point on the adjusted V plane.
12. (presently amended) The computerized method of claim 10 further comprising:
computing an adjusted U plane for the control point to provide a smooth transition between
the first U plane and the second U plane; and
computing an adjusted V plane for the control point to provide a smooth transition between
the first V plane and the second V plane.
13. (presently amended) The computerized method of 12 wherein adjusting the control point
using the first U plane and the second U plane and adjusting the control point using the first
V plane and the second V plane comprises projecting the control point on an intersection of
the adjusted U plane and the adjusted V plane.
14. (cancelled.)
15. (cancelled.)
16. (presently amended) The computerized method of claim 1 further comprising repeating the
first adjusting step, second adjusting step, and computing step for each point that is not along
the first edge in the U direction, second edge in the U direction, third edge in the V direction,
and fourth edge in the V direction.

17. (presently amended) A computerized method for manipulating a plurality of control points, the plurality of control points defining a surface and forming a plurality of rows along two non-parallel directions U and V, the method comprising:
determining if a row of control points corresponding to a first edge along the U direction belongs in a first U plane;
determining if a row of control points corresponding to a second edge along the U direction belongs in a second U plane; and
adjusting control points using the first U plane and the second U plane, wherein the adjustment only occurs if the row of control points corresponding to the first edge along the U direction belongs in the first U plane and the row of control points corresponding to the second edge along the U direction belongs in the second U plane;
wherein the surface is selected from the group consisting of a Béziars surface and a Nurbs surface, and wherein the surface is represented in a CAD system.
18. (cancelled.)
19. (cancelled.)
20. (presently amended) The computerized method of claim 17 wherein the surface comprises a three-dimensional surface.
21. (presently amended) The computerized method of claim 18 further comprising:
computing an adjusted U plane for the control point to provide a smooth transition between the first U plane and the second U plane;
wherein adjusting the control point using the first U plane and the second U plane comprises projecting the control point on the adjusted U plane.

22. (presently amended) The computerized method of claim 18 further comprising:

determining if a row of control points corresponding to a first edge along the V direction belongs in a first V plane;
determining if a row of control points corresponding to a second edge along the V direction belongs in a second V plane; and
adjusting the control point using the first V plane and the second V plane, wherein the adjustment only occurs if the row of control points corresponding to the first edge along the V direction belongs in the first V plane and the row of control points corresponding to the second edge along the V direction belongs in the second V plane.

23. (presently amended) The computerized method of claim 22 further comprising:

computing an adjusted V plane for the control point to provide a smooth transition between the first V plane and the second V plane;
wherein adjusting the control point using the first V plane and the second V plane comprises projecting the control point on the adjusted V plane.

24. (presently amended) The computerized method of claim 22 further comprising:

computing an adjusted U plane for the control point to provide a smooth transition between the first U plane and the second U plane; and
computing an adjusted V plane for the control point to provide a smooth transition between the first V plane and the second V plane.

25. (presently amended) The computerized method of 24 wherein adjusting the control point using the first U plane and the second U plane and adjusting the control point using the first V plane and the second V plane comprises projecting the control point on an intersection of the adjusted U plane and the adjusted V plane.

26. (Cancelled)

27. (cancelled)

28. (presently amended) A computerized method for manipulating a plurality of control points, the plurality of control points defining a surface and forming a plurality of rows along two non-parallel directions U and V, the method comprising:
determining if a row of control points corresponding to a first edge along the U direction belongs in a first U plane;
determining if a row of control points corresponding to a second edge along the U direction belongs in a second U plane; and
constraining the control points using the first U plane and the second U plane, wherein the constraining only occurs if the row of control points corresponding to a first edge along the U direction belongs in the first U plane and the row of control points corresponding to the second edge along the U direction belongs in the second U plane;
wherein the surface is selected from the group consisting of a Béziars surface and a Nurbs surface, and wherein the surface is represented in a CAD system.

29. (cancelled.)

30. (cancelled.)

31. (presently amended) The computerized method of claim 28 wherein the surface comprises a three-dimensional surface.

32. (presently amended) The computerized method of claim 28 further comprising:

computing an adjusted U plane for the control point to provide a smooth transition between the first U plane and the second U plane;
wherein constraining the control point using the first U plane and the second U plane comprises constraining the control point on the adjusted U plane.

33. (presently amended) The computerized method of claim 28 further comprising:

determining if a row of control points corresponding to a first edge along the V direction belongs in a first V plane;
determining if a row of control points corresponding to a second edge along the V direction belongs in a second V plane; and
constraining the control point using the first V plane and the second V plane, wherein the constraining only occurs if the row of control points corresponding to a first edge along the V direction belongs in the first V plane and the row of control points corresponding to the second edge along the V direction belongs in the second V plane.

34. (presently amended) The computerized method of claim 33 further comprising:

computing an adjusted V plane for the control point to provide a smooth transition between the first V plane and the second V plane;
wherein adjusting the control point using the first V plane and the second V plane comprises constraining the control point on the adjusted V plane.

35. (presently amended) The computerized method of claim 33 further comprising:

computing an adjusted U plane for the control point to provide a smooth transition between the first U plane and the second U plane; and
computing an adjusted V plane for the control point to provide a smooth transition between the first V plane and the second V plane.

36. (presently amended) The computerized method of 35 wherein constraining the control point using the first U plane and the second U plane and constraining the control point using the first V plane and the second V plane comprises constraining the control point to an intersection of the adjusted U plane and the adjusted V plane.
37. (cancelled.)
38. (cancelled.)
39. (previously amended) A computer system for manipulating a plurality of control points, the plurality of control points forming a plurality of rows along two non-parallel directions U and V, the system comprising:
a computer, wherein the computer comprises a memory and a processor; and
executable software residing in the computer memory wherein the software is operative with the processor to:
adjust the position of a control point in an intermediary row in the U direction to provide a smooth transition from the row of control points corresponding to a first edge along the U direction to a row of control points corresponding to a second edge along the U direction while retaining positions of control points in said first and second edges;
adjust the position of the control point in an intermediary row in the V direction to provide a smooth transition from the row of control points corresponding to a first edge along the V direction to a row of control points corresponding to a second edge along the V direction while retaining positions of control points in said first and second edges; and

compute the new position of the control point based on the corresponding adjusted positions of the control point in the intermediary row in the U direction and the control points in the intermediary row in the V direction.

40. (cancelled.)

41. (previously amended) A computer system for manipulating a plurality of control points, the plurality of control points forming a plurality of rows along two non-parallel directions U and V, the system comprising:

a computer, wherein the computer comprises a memory and a processor; and
executable software residing in the computer memory wherein the software is operative with the processor to:

determine if a row of control points corresponding to a first edge along the U direction belongs in a first U plane;

determine if a row of control points corresponding to a second edge along the U direction belongs in a second U plane; and

adjust the control point using the first U plane and the second U plane, wherein the adjustment only occurs if the row of control points corresponding to the first edge along the U direction belongs in the first U plane and the row of control points corresponding to the second edge along the U direction belongs in the second U plane.

42. (cancelled.)

43. (previously amended) A computer system for manipulating a plurality of control points, the plurality of control points forming a plurality of rows along two non-parallel directions U and V, the system comprising:

a computer, wherein the computer comprises a memory and a processor; and
executable software residing in the computer memory wherein the software is operative with the processor to:

determine if a row of control points corresponding to a first edge along the U direction
belongs in a first U plane;

determine if a row of control points corresponding to a second edge along the U direction
belongs in a second U plane; and

constrain the control point using the first U plane and the second U plane, wherein the
constraining only occurs if the row of control points corresponding to a first edge
along the U direction belongs in the first U plane and the row of control points
corresponding to the second edge along the U direction belongs in the second U
plane.

44. (cancelled.)